# Redshift space distortions and The growth of cosmic structure

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# Outline

- Introduction
  - Why, what, where, ...
- The simplest model.
  - Supercluster infall: the Kaiser factor.
  - Virial motions: Fingers-of-God.
- Beyond the simplest model.
  - What about configuration space?
  - Difficulties in modeling RSD.
  - Insights from N-body.
  - Some new ideas.
- Conclusions.

# RSD: Why

- What you observe in a redshift survey is the density field in redshift space!
  - A combination of density and velocity fields.
- Tests GI.
  - Structure growth driven by motion of matter and inhibited by expansion.
- Constrains GR.
  - Knowing a(t) and  $\rho_i$ , GR provides prediction for growth rate.
  - In combination with lensing measures  $\Phi$  and  $\Psi$ .
- Measures "interesting" numbers.
  - Constrains H(z), DE,  $m_v$ , etc.
- Surveys like BOSS can make percent level measurements – would like to have theory to compare to!
- Fun problem!

### RSD: What not

- Throughout I will be making the "distant" observer, and plane-parallel approximations.
- It is possible to drop this approximation and use spherical coordinates with *r* rather than Cartesian coordinates with *z*.
- References:
  - Fisher et al. (1994).
  - Heavens & Taylor (1995).
  - Papai & Szapudi (2008).
- Natural basis is tri-polar spherical harmonics.
- Correlation function depends on full triangle, not just on separation and angle to line-of-sight.

### **RSD:** What

- When making a 3D map of the Universe the 3<sup>rd</sup> dimension (radial distance) is usually obtained from a redshift using Hubble's law or its generalization.
  - Focus here on spectroscopic measurements.
  - If photometric redshift uses a break or line, then it will be similarly contaminated. If it uses magnitudes it won't be.
- Redshift measures a combination of "Hubble recession" and "peculiar velocity".

$$v_{\rm obs} = Hr + v_{\rm pec} \implies \chi_{\rm obs} = \chi_{\rm true} + \frac{v_{\rm pec}}{aH}$$
  
(often work in units where aH=1)

### Redshift space distortions

...depend on non-linear density and velocity fields, which are correlated.

Velocities enhance power on large scales and suppress power on small scales. Coherent infall ↓↓↓↓↓↓↓ ↑↑↑↑↑↑↑



Random (thermal) motion



### Redshift space distortions

Anisotropic correlation function



Line-of-sight selects out a special direction and breaks rotational symmetry of underlying correlations. We observe

anisotropic clustering.

Amount of anisotropy is related to rate of growth of structure.

### Power spectrum

- Mass conservation+distant observer +potential flow:
  - $\delta_k^{s} = [1 + f\mu^2]\delta_k^{r}$ . f=dln $\delta$ /dlna ~ rate of growth.
- If we square the density perturbation we obtain the power spectrum:

 $- P^{s}(k,\mu)=[1+f\mu^{2}]^{2} P^{r}(k)$ 

• For biased tracers (e.g. galaxies/halos) we can assume  $\delta_{obj} = b\delta_{mass}$  (and  $\theta_{obj} = \theta_{mass}$ ).  $- P^{s}(k,\mu) = [b+f\mu^{2}]^{2} P^{r}(k) = b^{2}[1+\beta\mu^{2}]^{2} P^{r}(k)$ 

### Fingers-of-god

- This neglects the motion of particles/galaxies inside "virialized" dark matter halos.
- These give rise to fingers-of-god which suppress power at high *k*.
- Peacock (1992) 1<sup>st</sup> modeled this as Gaussian "noise" so that

 $-P^{s}(k, \mu) = P^{r}(k) [b+f\mu^{2}]^{2} Exp[-k^{2}\mu^{2}\sigma^{2}]$ 

- Sometimes see this written as  $P_{\delta\delta} + P_{\delta\theta} + P_{\theta\theta}$  times Gaussians or Lorentzians.
  - Beware: no more general than linear theory!

### Legendre expansion

Rather than deal with a 2D function we frequently expand the angular dependence in a series of Legendre polynomials.

$$\begin{aligned} \Delta^2(k, \hat{k} \cdot \hat{z}) &\equiv \frac{k^3 P(k, \mu)}{2\pi^2} = \sum_{\ell} \Delta^2_{\ell}(k) L_{\ell}(\mu) \\ \xi(r, \hat{r} \cdot \hat{z}) &\equiv \sum_{\ell} \xi_{\ell}(r) L_{\ell}(\hat{r} \cdot \hat{z}) \quad , \quad \xi_{\ell}(r) = i^{\ell} \int \frac{dk}{k} \; \Delta^2_{\ell}(k) j_{\ell}(kr) \end{aligned}$$

On large scales (k $\sigma$ <<1) this series truncates quite quickly.

$$\begin{pmatrix} \Delta_0^2(k) \\ \Delta_2^2(k) \\ \Delta_4^2(k) \end{pmatrix} = \Delta^2(k) \begin{pmatrix} b^2 + \frac{2}{3}bf + \frac{1}{5}f^2 \\ \frac{4}{3}bf + \frac{4}{7}f^2 \\ \frac{8}{35}f^2 \end{pmatrix}$$

Typically only measure (well) *I*=0, 2.

We will work mostly in configuration space ...

# Widely used

	Model	Damping	Fitted parameters	Reference
1.	Empirical Lorentzian with linear $P_{\delta\delta}(k)$	Variable	$f, b, \sigma_v$	e.g. Hatton & Cole (1998)
2.	Empirical Lorentzian with non-linear $P_{\delta\delta}(k)$	Variable	$f, b, \sigma_v$	
3.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 1-loop SPT	None	f, b	e.g. Vishniac (1983), Juszkiewicz et al. (1984)
4.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 1-loop SPT	Variable	$f, b, \sigma_v$	
5.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 1-loop SPT	Linear	f, b	
6.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 1-loop RPT	None	f, b	Crocce & Scoccimarro (2006)
7.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 1-loop RPT	Linear	f, b	
8.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 2-loop RPT	None	f, b	
9.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 2-loop RPT	Variable	f, b	
10.	$P_{\delta\delta}, P_{\delta\theta}, P_{\theta\theta}$ from 2-loop RPT	Linear	f, b	
11.	$P(k,\mu)$ from 1-loop SPT	None	f, b	Matsubara (2008)
12.	$P(k,\mu)$ from 1-loop SPT	Linear	f, b	
13.	$P(k,\mu)$ with additional corrections	None	f, b	Taruya et al. (2010)
14.	$P(k,\mu)$ with additional corrections	Variable	$f, b, \sigma_v$	
15.	$P(k,\mu)$ with additional corrections	Linear	f, b	
16.	Fitting formulae from N-body simulations	None	f, b	Smith et al. (2003), Jennings et al. (2011)
17.	Fitting formulae from N-body simulations	Variable	$f, b, \sigma_v$	
18.	Fitting formulae from N-body simulations	Linear	f, b	

#### (Blake et al. 2012; WiggleZ RSD fitting)

### Kaiser is not particularly accurate



### In configuration space

- There are valuable insights to be gained by working in configuration, rather than Fourier, space.
- We begin to see why this is a hard problem ...

$$1 + \xi^{s}(R, Z) = \left\langle \int dy \ (1 + \delta_{1})(1 + \delta_{2})\delta^{(D)}(Z - y - v_{12}) \right\rangle$$
$$1 + \xi^{s}(R, Z) = \left\langle \int dy \ (1 + \delta_{1})(1 + \delta_{2}) \int \frac{d\kappa}{2\pi} e^{i\kappa(Z - y - v_{12})} \right\rangle$$

• Note all powers of the velocity field enter.

### Gaussian limit (Fisher, 1995, ApJ 448, 494)

If δ and v are Gaussian can do all of the expectation values.

$$1 + \xi^{s}(R, Z) = \int \frac{dy}{\sqrt{2\pi\sigma_{12}^{2}(y)}} \exp\left[-\frac{(Z-y)^{2}}{2\sigma_{12}^{2}(y)}\right] \times \left[1 + \xi^{r}(r) + \frac{y}{r}\frac{(Z-y)v_{12}(r)}{\sigma_{12}^{2}(y)} - \frac{1}{4}\frac{y^{2}}{r^{2}}\frac{v_{12}^{2}(r)}{\sigma_{12}^{2}(y)}\left(1 - \frac{(Z-y)^{2}}{\sigma_{12}^{2}(y)}\right)\right]$$

Expanding around y=Z:

$$\xi^{s}(R,Z) = \xi^{r}(s) - \left. \frac{d}{dy} \left[ v_{12}(r) \frac{y}{r} \right] \right|_{y=Z} + \frac{1}{2} \left. \frac{d^{2}}{dy^{2}} \left[ \sigma_{12}^{2}(y) \right] \right|_{y=Z}$$

Linear theory: configuration space (Fisher, 1995, ApJ 448, 494)

- One can show that this expansion agrees with the Kaiser formula.
- Two important points come out of this way of looking at the problem:
  - Correlation between  $\delta$  and v leads to  $v_{12}$ .
  - LOS velocity dispersion is scale- and orientationdependent.
- By Taylor expanding about r=s we see that ξ<sup>s</sup> depends on the 1<sup>st</sup> and 2<sup>nd</sup> derivative of velocity statistics.

### Two forms of non-linearity

- Part of the difficulty is that we are dealing with two forms of non-linearity.
  - The velocity field is non-linear.
  - The mapping from real- to redshift-space is nonlinear.
- These two forms of non-linearity interact, and can partially cancel.
- They also depend on parameters differently.
- This can lead to a lot of confusion ...

### Velocity field is nonlinear



### Non-linear mapping?



Want a fully non-linear "toy model", like spherical top-hat collapse, to gain some intuition ...

# A model for the redshift-space clustering of halos

- We would like to develop a model capable of describing the redshift space clustering of halos over the widest range of scales.
- This will form the 1<sup>st</sup> step in a model for galaxies, but it also interesting in its own right.
- The model should try to treat the "non-linear mapping" part of the problem non-perturbatively.
- We will start with a toy model and then add realism ...

# Why halos?

- Are the building blocks of large-scale structure.
- Galaxies live there!
- Halos occupy "special" places in the density field.
  - $\theta$  is a volume-averaged statistic.
- Dependence on halo bias is complex.
  - Studies of matter correlations not easily generalized!

### The correlation function of halos



The correlation function of halo centers doesn't have strong fingers of god, but still has "squashing" at large scales.

Note RSD is degenerate with A-P.

### Halo model

- There are multiple insights into RSD which can be obtained by thinking of the problem in a halo model language.
- This has been developed in a number of papers
  - White (2001), Seljak (2001), Berlind et al. (2001),
    Tinker, Weinberg & Zheng (2006), Tinker (2007).
- This will take us too far afield for now ...

# Scale-dependent Gaussian streaming model

Let's go back to the exact result for a Gaussian field, a la Fisher:

$$1 + \xi^{s}(R, Z) = \int \frac{dy}{\sqrt{2\pi\sigma_{12}^{2}(y)}} \exp\left[-\frac{(Z-y)^{2}}{2\sigma_{12}^{2}(y)}\right] \times \left[1 + \xi^{r}(r) + \frac{y}{r} \frac{(Z-y)v_{12}(r)}{\sigma_{12}^{2}(y)} - \frac{1}{4} \frac{y^{2}}{r^{2}} \frac{v_{12}^{2}(r)}{\sigma_{12}^{2}(y)} \left(1 - \frac{(Z-y)^{2}}{\sigma_{12}^{2}(y)}\right)\right]$$

Looks convolution-like, but with a scale-dependent  $v_{12}$  and  $\sigma$ . Also, want to resum  $v_{12}$  into the exponential ...

Scale-dependent Gaussian  
streaming model/ansatz  
$$1 + \xi(R, Z) = \int dy \ [1 + \xi(r)] \mathcal{P}(v = Z - y, \mathbf{r})$$

Note: *not* a convolution because of (important!) *r* dependence or kernel.

Non-perturbative mapping.

If lowest moments of *P* set by linear theory, agrees at linear order with Kaiser. Approximate *P* as Gaussian ...



### Gaussian ansatz



### Halo samples

• We compare our theoretical models with 3 halo/galaxy samples taken from N-body simulations.

Sample	lgM	b	bLPT	n (10 <sup>-4</sup> )
High	>13.4	2.67	2.79	0.76
Low	12.48-12.78	1.41	1.43	4.04
HOD	-	1.81	1.90	3.25

### Testing the ansatz



# The mapping



Note, the behavior of the quadrupole is particularly affected by the non-linear mapping. The effect of non-linear velocities is to suppress  $\xi_2$  (by ~10%, significant!). The mapping causes the enhancement. This effect is tracer/ bias dependent!

### An analytic model

This has all relied on input from N-body. Can we do an analytic model? Try "standard" perturbation theory<sup>\*</sup> for the v<sub>12</sub> and  $\sigma$  terms ...





Gaussian streaming model is better ... but still suffers from problems on small scales.

### The "b<sup>3</sup>" term?

- One of the more interesting things to come out of this ansatz is the existence of a "b<sup>3</sup>" term.
  - Numerically quite important when b~2.
  - Another reason why mass results can be very misleading.
  - But hard to understand (naively) from

$$1 + \xi^s(R, Z) = \left\langle \int dy \ (1 + \delta_1)(1 + \delta_2) \int \frac{d\kappa}{2\pi} e^{i\kappa(Z - y - v_{12})} \right\rangle$$

- Where does it come from?

# Streaming model

 In the streaming model this term can be seen by expanding the exponential around s=r which gives a term

$$-\frac{d}{dy}\left[\xi \ v_{12}\right]$$

- Since  $\xi \sim b^2$  and  $v \sim b$  this term scales as  $b^3$ .
  - More highly biased tracers have more net infall and more clustering.
- But, we "put" the v<sub>12</sub> into the exponential by hand ... we didn't derive it.
- Can we understand where this comes from ...?

# Lagrangian perturbation theory

- A different approach to PT, which has been radically extended recently by Matsubara (and is *very* useful for BAO):
  - Buchert89, Moutarde++91, Bouchet++92, Catelan95, Hivon++95.
  - Matsubara (2008a; PRD, 77, 063530)
  - Matsubara (2008b; PRD, 78, 083519)
- Relates the current (Eulerian) position of a mass element, x, to its initial (Lagrangian) position, q, through a displacement vector field, Ψ.

### Lagrangian perturbation theory

$$\begin{split} \delta(\mathbf{x}) &= \int d^3 q \, \, \delta_D(\mathbf{x} - \mathbf{q} - \boldsymbol{\Psi}) - 1 \\ \delta(\mathbf{k}) &= \int d^3 q \, \, e^{-i\mathbf{k}\cdot\mathbf{q}} \left( e^{-i\mathbf{k}\cdot\boldsymbol{\Psi}(\mathbf{q})} - 1 \right) \, . \end{split}$$

$$\frac{d^2 \Psi}{dt^2} + 2H \frac{d \Psi}{dt} = -\nabla_x \phi \left[ \mathbf{q} + \Psi(\mathbf{q}) \right]$$

$$\Psi^{(n)}(\mathbf{k}) = \frac{i}{n!} \int \prod_{i=1}^{n} \left[ \frac{d^{3}k_{i}}{(2\pi)^{3}} \right] (2\pi)^{3} \delta_{D} \left( \sum_{i} \mathbf{k}_{i} - \mathbf{k} \right)$$
$$\times \mathbf{L}^{(n)}(\mathbf{k}_{1}, \cdots, \mathbf{k}_{n}, \mathbf{k}) \delta_{0}(\mathbf{k}_{1}) \cdots \delta_{0}(\mathbf{k}_{n})$$

### LPT power spectrum

- We can use the expression for  $\delta_{\textbf{k}}$  to write

$$P(k) = \int d^3q \ e^{-i\vec{k}\cdot\vec{q}} \left(\left\langle e^{-i\vec{k}\cdot\Delta\vec{\Psi}}\right\rangle - 1\right)$$

- where  $\Delta \Psi = \Psi(\mathbf{q}) \Psi(0)$ . [Note translational invariance.]
- Expanding the exponential and plugging in for  $\Psi^{(n)}$  gives the usual results.

• **BUT** Matsubara suggested a different and very clever approach.

### Cumulants

- The cumulant expansion theorem allows us to write the expectation value of the exponential in terms of the exponential of expectation values.
- Expand the terms [Ψ(q<sub>1</sub>)-Ψ(q<sub>2</sub>)]<sup>N</sup> using the binomial theorem.
- There are two types of terms:
  - Those depending on  $\Psi$  at same point.
    - This is independent of position and can be factored out of the integral.
  - Those depending on  $\Psi$  at different points.
    - These can be expanded as in the usual treatment.
# Example

- Imagine  $\Psi$  is Gaussian with mean zero.
- For such a Gaussian:  $\langle e^{\Psi} \rangle = \exp[\sigma^2/2]$ .

$$P(k) = \int d^3 q e^{-i\mathbf{k}\cdot\mathbf{q}} \left( \left\langle e^{-ik_i \Delta \Psi_i(\mathbf{q})} \right\rangle - 1 \right)$$

$$\left\langle e^{-i\mathbf{k}\cdot\Delta\Psi(q)}\right\rangle = \exp\left[-\frac{1}{2}k_ik_j\left\langle\Delta\Psi_i(\mathbf{q})\Delta\Psi_j(\mathbf{q})\right\rangle\right]$$

$$k_{i}k_{j} \left\langle \Delta \Psi_{i}(\mathbf{q}) \Delta \Psi_{j}(\mathbf{q}) \right\rangle = 2k_{i}^{2} \left\langle \Psi_{i}^{2}(\mathbf{0}) \right\rangle - 2k_{i}k_{j}\xi_{ij}(\mathbf{q})$$

$$\uparrow$$
Keep exponentiated, Expand call  $\Sigma^{2}$ .

## Resummed LPT

• The first corrections to the power spectrum are then:

$$P(k) = e^{-(k\Sigma)^2/2} \left[ P_L(k) + P^{(2,2)}(k) + \widetilde{P}^{(1,3)}(k) \right],$$

- where P<sup>(2,2)</sup> is as in SPT but part of P<sup>(1,3)</sup> has been "resummed" into the exponential prefactor.
- The exponential prefactor is identical to that obtained from
  - The peak-background split (Eisenstein++07)
  - Renormalized Perturbation Theory (Crocce++08).
- Does a great job of explaining the broadening and shifting of the BAO feature in ξ(r) and also what happens with reconstruction.
- But breaks down on smaller scales ...

# Beyond real-space mass

- One of the more impressive features of Matsubara's approach is that it can gracefully handle both biased tracers and redshift space distortions.
- In redshift space, in the plane-parallel limit,

$$\Psi \to \Psi + \frac{\widehat{\mathbf{z}} \cdot \dot{\Psi}}{H} \ \widehat{z} = R \Psi$$

• In PT 
$$\Psi^{(n)} \propto D^n \Rightarrow R_{ij}^{(n)} = \delta_{ij} + nf \, \hat{z}_i \hat{z}_j$$

• Again we're going to leave the zero-lag piece exponentiated so that the prefactor contains

 $k_{i}k_{j}R_{ia}R_{jb}\delta_{ab} = (k_{a} + fk\mu\hat{z}_{a})(k_{a} + fk\mu\hat{z}_{a}) = k^{2}\left[1 + f(f+2)\mu^{2}\right]$ 

 while the ξ(r) piece, when FTed, becomes the usual Kaiser expression plus higher order terms.

# Beyond real-space mass

- One of the more impressive features of Matsubara's approach is that it can gracefully handle both biased tracers and redshift space distortions.
- For bias local in Lagrangian space:

$$\delta_{\rm obj}(\mathbf{x}) = \int d^3 q \ F[\delta_L(\mathbf{q})] \,\delta_D(\mathbf{x} - \mathbf{q} - \mathbf{\Psi})$$

• we obtain

$$P(k) = \int d^3 q \ e^{-i\mathbf{k}\cdot\mathbf{q}} \left[ \int \frac{d\lambda_1}{2\pi} \frac{d\lambda_2}{2\pi} F(\lambda_1) F(\lambda_2) \left\langle e^{i[\lambda_1\delta_L(\mathbf{q}_1) + \lambda_2\delta_L(\mathbf{q}_2)] + i\mathbf{k}\cdot\Delta\Psi} \right\rangle - 1 \right]$$

- which can be massaged with the same tricks as we used for the mass.
- If we assume halos/galaxies form at peaks of the initial density field ("peaks bias") then explicit expressions for the integrals of F exist.

#### Peaks bias

- Expanding the exponential pulls down powers of  $\lambda$ .
- FT of terms like  $\lambda^n F(\lambda)$  give  $F^{(n)}$
- The averages of F' and F'' over the density distribution take the place of "bias" terms

 $-b_1$  and  $b_2$  in standard perturbation theory.

• If we assume halos form at the peaks of the initial density field we can obtain:

$$b_1 = \frac{\nu^2 - 1}{\delta_c} \quad , \quad b_2 = \frac{\nu^4 - 3\nu^2}{\delta_c^2} \approx b_1^2$$

# Example: Zel'dovich

- Let's consider the lowest order expression
  - Zel'dovich approximation.

$$\Psi(\mathbf{q}) = \Psi^{(1)}(\mathbf{q}) = \int \frac{d^3k}{(2\pi)^3} \ e^{i\mathbf{k}\cdot\mathbf{q}} \ \frac{i\mathbf{k}}{k^2} \ \delta_0(\mathbf{k})$$

 Have to plug this into 1+ξ formula, Taylor expand terms in the exponential, do λ integrals, ...

# Convolution LPT?

- Matsubara separates out the q-independent piece of the 2-point function  $<\Delta \Psi_i \Delta \Psi_i >$
- Instead keep all of  $<\Delta \Psi_i \Delta \Psi_i >$  (and  $\sigma_R$ ) exponentiated.
  - Expand the rest.
  - Do some algebra.
  - Evaluate convolution integral numerically.
  - This is a partial resummation of Matsubara's expression.
- Guarantees we recover the Zel'dovich limit as 0<sup>th</sup> order CLPT (for the matter).
  - Eulerian and LPT require an  $\infty$  number of terms.
  - Many advantages: as emphasized recently by Tassev & Zaldarriaga
- Can use tricks to rewrite the ZA as a pure convolution, and figure out exactly what is being "smeared" by the Gaussian smoothing.

## Matter & Zel'dovich approximation

$$A_{ij} = \langle \Delta \Psi_i \Delta \Psi_j \rangle = B + C = 2\sigma^2 \delta_{ij} + C$$

$$1 + \xi^{ZA}(\mathbf{r}) = \int \frac{d^3 \mathbf{q}}{(2\pi)^{3/2} |A|^{1/2}} e^{-(\mathbf{r} - \mathbf{q})A^{-1}(\mathbf{r} - \mathbf{q})/2}$$
$$= \int \frac{d^3 \mathbf{q}}{(2\pi)^{3/2} |B|^{1/2}} e^{-(\mathbf{r} - \mathbf{q})B^{-1}(\mathbf{r} - \mathbf{q})/2} \left[1 + \chi(\mathbf{q})\right]$$

#### Matter: Real: Monopole



#### Matter: Red: Monopole



### Matter: Quadrupole









#### Halos: Red: Monopole





# A combination of approaches? $Z(r,J) = \int d^3q \int \frac{d^3k}{(2\pi)^3} e^{ik \cdot (q-r)} \int \frac{d\lambda_1}{2\pi} \frac{d\lambda_2}{2\pi} \tilde{F}(\lambda_1) \tilde{F}(\lambda_2) K(q,k,\lambda_1,\lambda_2,J)$

$$K = \left\langle e^{i(\lambda_1 \delta_1 + \lambda_2 \delta_2 + k \cdot \Delta + J \cdot \dot{\Delta})} \right\rangle$$

$$1 + \xi(r) = Z(r, J = 0) \equiv Z_0(r),$$
$$v_{12,\alpha}(r) = \frac{\partial Z}{\partial J_\alpha} \Big|_{J=0} \equiv Z_{0,\alpha}(r),$$
$$D_{\alpha\beta}(r) = \frac{\partial^2 Z}{\partial J_\alpha \partial J_\beta} \Big|_{J=0} \equiv Z_{0,\alpha\beta}(r)$$

... plus streaming model ansatz.

# From halos to galaxies

- In principle just another convolution
  - Intra-halo PDF.
- In practice need to model cs, ss<sup>(1h)</sup> and ss<sup>(2h)</sup>.
- A difficult problem in principle, since have fingers-of-god mixing small and large scales.
  - Our model for  $\boldsymbol{\xi}$  falls apart at small scales...
- On quasilinear scales things simplify drastically.
  - Classical FoG unimportant.
  - Remaining effect can be absorbed into a single Gaussian dispersion which can be marginalized over.

# Conclusions

- Redshift space distortions arise in a number of contexts in cosmology.
  - Fundamental questions about structure formation.
  - Constraining cosmological parameters.
  - Testing the paradigm.
- Linear theory doesn't work very well.
- Two types of non-linearity.
  - Non-linear dynamics and non-linear maps.
- Bias dependence can be complex.
- We are developing a new formalism for handling the redshift space correlation function of biased tracers.
  - Stay tuned!

