Wide angle effects in redshift surveys (a.k.a. "What the heck are we measuring?") Emanuele Castorina & Martin White (UCB/LBNL)

June 2018

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

## Redshift space

- The observed redshift of a cosmological object has contributions from the Hubble expansion and the peculiar velocity.
- We convert *z* to a distance using a distance-redshift relation.
- Thus in redshift surveys we measure not the true position of objects but their redshift-space position:

$$\mathbf{s} = \mathbf{r} + \hat{r} \cdot \mathbf{v} / (aH) \hat{r}$$

- This is both a blessing and a curse:
  - it makes the analysis more complicated, but
  - it gives access to more information.

[Throughout all my 3D positions will be in redshift space. Real-space quantities will be called out specifically.]

## Plane-parallel approximation

- Each redshift-space position depends upon 1 component of velocity.
- For narrow fields or objects at high redshift, the plane-parallel or distant observer approximation(s) are valid:
  - we can replace  $\hat{s}$  with a fixed vector (conventionally  $\hat{z}$ ).
  - all objects 'probe' same component of velocity.
- This is the standard assumption/approximation in the field, and is nearly ubiquitous in theory and data analysis.
- This assumption restores a symmetry which is absent in the full calculation.

We are not *always* in that limit, and it is interesting to ask 'fundamental' questions about what we're measuring and how that limit is approached.

## History

This is an **old** question, which has been explored since the first papers on redshift-space distortions. We are treading some new ground, but building upon a vast amount of earlier work!

Hamilton (1992); Hamilton & Culhane (1996); Zaroubi & Hoffman (1996); Szalay et al. (1998); ···; Raccanelli et al. (2014); Yoo & Seljak (2015); Samushia et al. (2015); Reimberg et al. (2016); Castorina & White (2018a,b).

[I will concentrate on 'physical' wide angle effects, not those induced by the survey selection function – see paper for the latter. Ditto for lightcone effects and h.o. functions.]

## The two-point function

- Observer viewing two galaxies, at s<sub>1</sub> and s<sub>2</sub>.
- Separation vector  $\vec{s} = \vec{s_1} \vec{s_2}$ .
- Opening angle θ.
- ► Line of sight = angle bisector (d)
- Define  $\mu = \cos \phi = \hat{s} \cdot \hat{d}.$

The BAO scale at z = 0.2has  $\theta \simeq 0.2$ ; at z = 1 have  $\theta \simeq 0.05$ .



## The two-point function

- \$\heta\$ is different for the two legs, we've lost translational invariance

   the observation picks a preferred origin (us).
- Breaks translational invariance down into remaining rotation of d̂ and rotation about d̂.
- Clustering depends on triangle:

 $\xi = \xi(\triangle) \neq \xi(\mathbf{s})$ 



## **Triangles!**

Several ways to specify the triangle, starting from  $\mathbf{s}_1$  and  $\mathbf{s}_2$  and allowing rotations of  $\hat{d}$  and around  $\hat{d}$ :

- Use angle bisector, d, and relative coordinate, s = s<sub>1</sub> − s<sub>2</sub> to specify ξ(△) = ξ(s, d, μ = d̂ · ŝ).
- Same but using the mid-point as **d**.
- Same but using an end-point  $\mathbf{s}_1$  (or  $\mathbf{s}_2$ ) as  $\mathbf{d}$ .
- Give two side lengths and enclosed angle:  $\xi(s_1, s_2, \cos \theta)$ .
- Several others we won't need.

Can convert different conventions using Euclidean geometry theorems about triangles: *kind of fun if you're into that kind of thing*.

## Results - bisector

For the angle-bisector definition of **d** the effects in configuration space are small,  $\mathcal{O}(\theta^2)$ , but not negligible at high  $\ell$ :



#### Results - endpoint

The effects are much larger,  $\mathcal{O}(\theta)$ , for the endpoint definition:



▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

## Odd multipoles

...and the endpoint definition introduces odd multipoles:



▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

#### Power spectrum

#### How do I Fourier transform $\xi(\triangle)$ ?

Since we've lost the translational symmetry of the underlying problem, there is no longer an obvious P(k):

$$\langle \delta(\mathbf{k}_1) \delta^{\star}(\mathbf{k}_2) \rangle \neq (2\pi)^3 \delta^{(D)}(\mathbf{k}_1 - \mathbf{k}_2) P(\mathbf{k}_1)$$

- We need to take care in specifying what we mean by "the" power spectrum
  - Zarroubi & Hoffman 1996; Szalay++98; · · ·
- So what is it that we've measured when we quote P(k) in a redshift survey?
- What would a sensible definition look like?

#### Power spectrum

- We need to take care in specifying what we mean by "the" power spectrum
  - Zarroubi & Hoffman 1996; Szalay++98; · · ·
- A fruitful definition is a 'mixed' statistic:

$$P(\mathbf{k},\mathbf{d}) = \int d^3s \ e^{-i\mathbf{k}\cdot\mathbf{s}}\xi(\mathbf{s},\mathbf{d}) = \sum_{\ell n} (kd)^{-n} P_{\ell}^{(n)}(k) \mathcal{P}_{\ell}(\mu_k)$$

and the plane-parallel limit is  $kd \rightarrow \infty$ .

The multipoles of P and ξ are related by a Hankel transform:

$$P_\ell(k,d) = 4\pi (-i)^\ell \int s^2 ds \ \xi_\ell(s,d) j_\ell(ks)$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Most other definitions lead to difficulties...

#### Yamamoto estimator

- ▶ People usually compute  $P(\mathbf{k})$  using the 'Yamamoto' estimator.
- This is an approximation to  $\int (d^3d/V)P(\mathbf{k}; d)$ .
- ▶ P<sub>ℓ</sub> can be computed by summing over pairs, but this is slow and 'expensive'.
- ▶ People usually use end-point definition: d̂ = ŝ<sub>1</sub>, then the P<sub>ℓ</sub>(k) estimator factorizes and can use FFTs ...
- ... but it gives corrections at O(θ) rather than O(θ<sup>2</sup>) (and mixes Hankel transforms in a very non-trivial way).
- ► Corrections grow with *l*: possibly important if computing wedges or treating fiber assignment this way.

#### Power spectra



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ○臣 - の々ぐ

## Masks

We are familiar with a mask in a survey generating a 'window function'. Specifically if our density field is multiplied by  $W(\mathbf{x})$  (usually 0 or 1) then

$${\cal P}({f k}) = \int rac{d^3 q}{(2\pi)^3} {\cal P}({f q}) \left| \widetilde{W}({f k}-{f q}) 
ight|^2$$

However, this transition from multiplication to convolution assumes translational invariance – which is violated in wide-angle.

Leading order wide angle terms become important at the same scale as the mask does.

[Indications that this could matter for BOSS and future surveys]

#### Masks

Need to follow an approach which is a generalization of the "pseudo- $C_{\ell}$ " method used in CMB. For bisector-Yamamoto

$$\left\langle \hat{P}_{L}(k) \right\rangle \propto \sum_{\ell} \int \frac{d^{3}s_{1} d^{3}s_{2}}{V} W_{\ell}^{L}(s,d) \underbrace{\xi_{\ell}(s,d)}_{\int P(k')j_{\ell}(k's)} j_{L}(ks)$$

Note  $\xi_{\ell}(s)j_{L}(ks)$  is *not* a Hankel transform! One can compute  $W_{\ell}^{L}$  efficiently using randoms:

$$W_{\ell}^{L}(s,d) = \int rac{d\Omega_{1}d\Omega_{2}}{4\pi} W_{1}W_{2}\mathcal{P}_{\ell}(\hat{s}\cdot\hat{d})\mathcal{P}_{L}(\hat{s}\cdot\hat{d})$$

(sum over pairs of randoms, binning the integrand in bins of s,d).

[For the FFT estimator there are a few extra terms.]

## Power spectra - BOSS window



▲□ > ▲圖 > ▲ 臣 > ▲ 臣 > → 臣 = ∽ 9 Q ()~.

## Aside:

- This formalism could be useful for 21 cm interferometers which observe the sky with wide primary beams.
- It could be useful for 'nearby' surveys aimed at BAO or large-scale velocities.
- Also it offers a way of immunizing yourself against systematics which vary slowly with distance, e.g. purely angular systematics and a principled way to marginalize at the 2-point function level.
- It overcomes a big issue with the sFB formalism: covariances.

Fisher et al. (1994); Heaves & Taylor (1995); Tadros et al. (1999);
Taylor et al. (2001); Padmanabhan et al. (2001); Percival et al. (2004); Padmanabhan et al. (2007); ···; Yoo & Desjacques (2013); Pratten & Munshi (2013); Nicola et al. (2014); Liu et al. (2016); Passaglia et al. (2017).

## Conclusions

- Beyond plane-parallel what it is we're measuring requires some thought.
  - Outside of the distant observer limit  $\xi = \xi(\Delta)$  not  $\xi(\mathbf{s})$ .
  - There is no 'natural' P(k) definition, or even obvious plane-parallel limit.
  - Symmetry breaking!
- Effects are small, but not negligible.
  - Grow with  $\ell$  and s/d (i.e. large scale).
  - Analytic models work well, highlight issues.
- Standard FFT  $P_L(k)$  estimator has  $\mathcal{O}(\theta)$  corrections.
- Formalism for masks becomes more complex.
  - Could be seeing this already.
- Interesting connections with sFB, intensity mapping, mode marginalization, ...

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

# The End!

.

#### Plane parallel or distant observer limit

- The plane-parallel limit is regained in the limit  $d \to \infty$ .
- In the angle bisector definition we usually define x = s/d, so that ξ = ξ(s, x, μ). Expanding in power of x and in multipoles:

$$\xi(s,x,\mu) = \sum_{\ell n} x^n \, \xi_\ell^{(n)}(s) \mathcal{P}_\ell(\mu)$$

The plane-parallel limit is

$$\xi^{\mathrm{pp}} = \lim_{x \to 0} \xi(s, x, \mu) = \sum_{\ell} \xi^{(0)}_{\ell}(s) \mathcal{P}_{\ell}(\mu)$$

The BAO scale at z = 0.2 has  $\theta \simeq 0.2$ ; at z = 1 have  $\theta \simeq 0.05$ .

#### Plane parallel or distant observer limit

In linear theory

$$\xi_\ell^{(n)}(s,d) = \int rac{k^2 \, dk}{2\pi^2} (kd)^{-n} P_{ ext{lin}}(k) j_\ell(ks) \sim x^n \xi_\ell^{(0)}$$

- For the angle bisector or midpoint definitions, which are 'symmetric', the first correction comes in at O(θ<sup>2</sup>), or O(x<sup>2</sup>).
- For the endpoint convention the first correction is O(θ), however the correction can be expressed in terms of known terms – it contains no further signal.

• e.g. 
$$\xi_1(s, s_1) = -(3/5)(s/s_1)\xi_2^{\text{pp}}(s) + \cdots$$
  
• e.g.  $\xi_3(s, s_1) = (3/5)(s/s_1)\xi_2^{\text{pp}}(s) - (10/9)(s/s_1)\xi_4^{\text{pp}}(s) + \cdots$ 

## Zeldovich and wide angle effects

- Conveniently, wide-angle effects occur at large scales where we can use analytic techniques.
- All analytical results on wide-angle effects have assumed linear theory (with linear bias).
  - Reproduced and extended those results.
- Can compute ξ(△) precisely within the Zeldovich approximation, including complex bias modeling.
  - ► Tassev 2014 states this, but didn't pursue it.
- In Castorina & White (2018b) we give the full expressions and various limits.

► This allows one to beyond l = 4, and to include advection properly.

## Window function effects

Window vs. no-window at z = 0.38 for BOSS:



Courtesy: E. Castorina & F. Beutler

・ロト ・聞ト ・ヨト ・ヨト

臣

# MAPS I

- The last convention (side lengths and included angle) is the most obvious generalization of CMB formalism, and the most directly connected to observables:
  - ► *s<sub>i</sub>* are related to redshift and hence frequency,
  - $\theta$  is the observed angular separation.
- Normally you Legendre transform in angle to get the multi-frequency angular power spectrum (MAPS):

$$\xi(s_1, s_2, \cos heta) = \sum_\ell rac{2\ell+1}{4\pi} C_\ell(s_1, s_2) \mathcal{P}_\ell(\cos heta)$$

► Alternatively you can think of spherical transforming the slices at s<sub>1</sub> and s<sub>2</sub> into a<sub>ℓ1m1</sub>(s<sub>1</sub>) and a<sub>ℓ2m2</sub>(s<sub>2</sub>) then

$$\left\langle a_{\ell_1 m_1}^{\star}(s_1) a_{\ell_2 m_2}(s_2) \right\rangle = C_{\ell}(s_1, s_2) \delta_{\ell_1 \ell_2} \delta_{m_1 m_2}$$

► A further Hankel transform in the length of the legs gives C<sub>ℓ</sub>(k<sub>1</sub>, k<sub>2</sub>) [connection to sFB formalism of Heavens & Taylor (1995)].

#### MAPS: plane parallel limit

In the plane-parallel limit,  $C_\ell$  is a bit of a hybrid. Changing variables from  $s_1$  and  $s_2$  to  $d = (s_1 + s_2)/2$  and  $s_{\parallel} = s_1 - s_2$  we have

$$\begin{array}{lll} \mathcal{C}_{\ell}(s_{\parallel},d) &=& 2\pi \int d(\cos\theta) \; \xi(s,d,\mu) \mathcal{P}_{\ell}(\cos\theta) \\ &\simeq& 2\pi \int \tilde{\omega} d\tilde{\omega} \; \xi(s_{\perp},s_{\parallel},d) J_0(\ell\tilde{\omega}) & \left[\tilde{\omega}=2\sin\left(\frac{\theta}{2}\right)\right] \\ &\simeq& \int \frac{d^2 s_{\perp}}{d^2} \; \xi(s_{\parallel},s_{\perp},d) e^{i\mathbf{k}_{\perp}\cdot\mathbf{s}_{\perp}} \\ &\simeq& \int_0^\infty \frac{dk_{\parallel}}{\pi \; d^2} P(k_{\perp}=\ell/d,k_{\parallel}) \cos(k_{\parallel}s_{\parallel}) \end{array}$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

with  $s_{\parallel} = s\mu$  to lowest order in s/d (and  $\ell = k_{\perp}d$ ).

## MAPS: beyond plane-parallel

- Interestingly the high- $\ell$  moments come from aliasing of low L power through geometry, in the same way that high  $\ell$  in the CMB angular power spectrum can come from the density (L = 0) and velocity (L = 1) of the photon fluid.
- In Castorina & White (2018) we worked through the angular momentum addition to find the exact relation beyond plane-parallel:

$$C_{\ell}(\underbrace{k_{1},k_{2}}_{1D}) = \sum_{nL} \mathcal{M}_{\ell L}^{(n)}(k_{1},k_{2}) P_{L}(\underbrace{k_{2}}_{3D})$$

•  $\mathcal{M}_{\ell L}^{(n)}$  depends only on geometry, not cosmology.

#### Yamamoto estimator

In surveys P<sub>l</sub>(k) is usually computed using "the Yamamoto estimator":

$$P_L^Y(k) = (2L+1) \int \frac{d\Omega_k}{4\pi} \frac{d^3 s_1 d^3 s_2}{V} \delta(\mathbf{s}_1) \delta(\mathbf{s}_2) e^{-i\mathbf{k}\cdot\mathbf{s}} \mathcal{P}_L\left(\hat{k}\cdot\hat{d}\right)$$

- One can show that  $P_{\ell}^{Y} = \int (d^{3}d/V)P_{L}(k,d)$ .
- ► The 'full' Yamamoto estimator is very expensive to compute, so people usually use end-point definition: *d̂* = *ŝ*<sub>1</sub>.
- This allows the use of FFTs, ...
- ... but it gives corrections at O(θ) rather than O(θ<sup>2</sup>) and mixes Hankel transforms in a very non-trivial way.
- Corrections grow with L: possibly important if computing wedges or treating fiber assignment this way.